



FUZZY SUMMARISATION SYSTEM RESEARCH

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ABSTRACT: *This paper describes the implementation of fuzzy set theory and Fuz-zy Inference System (FIS) for prediction of electric load. The proposed technique utilizes fuzzy rules to incorporate historical weather and load data. The use of fuzzy logic effectively handles the load variations due to special events. The fuzzy logic has been extensively tested on actual data obtained from the Czech Electric Power Company (~CEZ) for 24-hour ahead prediction. Test results indicate that the fuzzy rule base can produce results better in accuracy than artificial neural networks (ANNs) method.*

Keywords: *fuzzy sets, fuzzification, fuzzy logic, fuzzy inference system, prediction implementation, employees.*

Fuzzy logic model has been selected as an alternative method for the load forecasting problem in this paper. It is a suitable technique in case when the historical data are not real numbers, but linguistic values. This paper presents the results of a preliminary investigation of the feasibility of use of a fuzzy logic model for short-term load forecasting. In this research, historical load and weather data are converted into fuzzy set theory to produce fuzzy forecasts and defuzzification is performed to generate a point estimate for system load.



DESCRIPTION OF FUZZY INFERENCE SYSTEM. Fuzzy set A is defined in terms (U, μ_A) , where U is relevant universal set and $\mu_A U < 0, 1 >$ is a membership function, which assigns each elements from U to fuzzy set A . The membership of the element $x \in U$ of a fuzzy set A is indicated $\mu_A(x)$. We call $F(U)$ the set of all fuzzy set. Then „classical“ set A is fuzzy set where: $\mu_A : U \rightarrow \{0, 1\}$. Thus $x \in A$, $\mu_A(x) = 1$ and $x \notin A$, $\mu_A(x) = 0$. Let $U_i, i = 1, 2, \dots, n$, be universals. Then fuzzy relation R on $U = U_1 \times U_2 \times \dots \times U_n$ is a fuzzy set R on universal U .

Fuzzy Inference System: One of the possible applications is a fuzzy inference system (FIS) (fuzzy regulator). There are a few types of regulators. We use the regulator of type $P : u = R(e)$ for our purposes, where the action values depend only on a regulation deviation:

Input variables: $E_i = (E_i, T(E_i), E_i, G, M), i = 1, \dots, n$.

Output variables: $U = (U, T(U), U, G, M)$.

We consider the fuzzy regulator as the statement of the type: $R = R_1$

We do not require the output of fuzzy regulator to be a set in many cases, but we require the concrete value $z_0 \in Z$, e.i. we want to make a defuzzification. The centroid method is the most frequently used method of defuzzification. The FIS defined in such a way is called Mamdani.

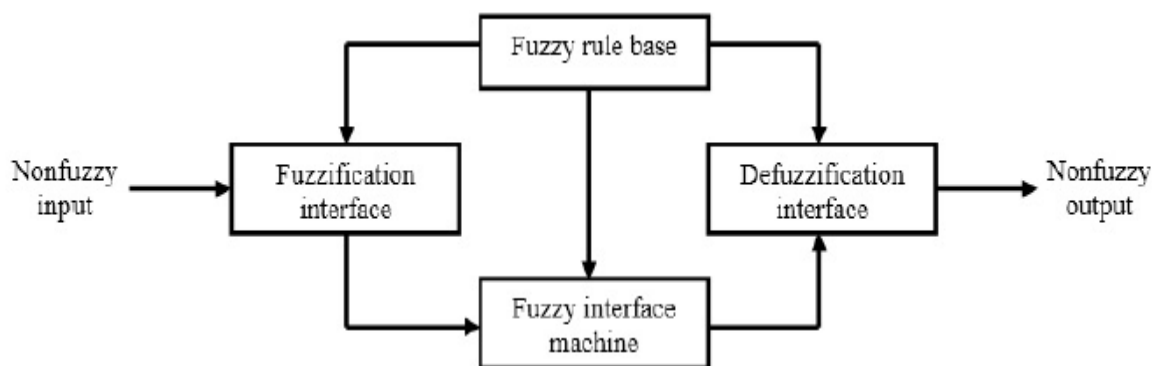


Fig. 1. Block diagram of a fuzzy inference system

DESCRIPTION FIS FOR PREDICTION OF LOAD

The four principal components of a fuzzy system is shown in Figure



The fuzzification interface performs a scale mapping that changes the range of values of input variables into corresponding universe of discourse. It also performs fuzzification that converts nonfuzzy (crisp) input data into suitable linguistic values, which may be viewed as labels of fuzzy sets. Fuzzy rule base, which consists of a set of linguistic control rules written in the form “If a set of conditions are satisfied, Then a set of consequences are inferred”. Fuzzy inference machine, which is a decision-making logic that employs rules from the fuzzy rule base to infer fuzzy control actions in response to fuzzified inputs. Defuzzification interface performs a scale mapping that converts the range of values of output variables into corresponding universe of discourse. It also performs defuzzification that yields a nonfuzzy (crisp) control action from an inferred fuzzy control action [2]. A commonly used defuzzification rule known as centroid method is used here, according to which the defuzzification interface produces a crisp output defined as the center of gravity of the distribution of possible actions. This centroid approach produces a numerical forecast sensitive to all the rules.

Various membership functions have been discussed, and for the particular application data sets, their effects on model performance have been demonstrated. The proposed model has been able to generate forecasts with a MAPE frequently below 2.8 % for working days, 3.6 % for weekends and 3.4 % for special days. The simulation results demonstrate the effectiveness of the fuzzy model for 24-hour ahead prediction.

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